Height-Diameter curves from longitudinal data

Lauri Mehtätalo lauri.mehtatalo@yale.edu

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The aim of this study

The aim was to estimate such a Height-Diameter model that could be used for prediction using the fixed predictors and height sample tree measurements from various points in time.

More specifically, the model should be able to

1. predict H-D curve when no sample tree heights are known,

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[The aim of the study](#page-5-0) [Study material](#page-6-0)

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[The aim of the study](#page-2-0) [Study material](#page-6-0)

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- 3. use old height sample trees to improve the prediction of current point in time,
- 4. predict the H-D curve in the future,

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[The aim of the study](#page-2-0) [Study material](#page-7-0)

- \triangleright Data includes (almost) randomly selected stands from all around the Finland
- \triangleright We are using Norway spruces, which is a shade tolerant tree species

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[The aim of the study](#page-2-0) [Study material](#page-6-0)

- \triangleright Data includes (almost) randomly selected stands from all around the Finland
- \triangleright We are using Norway spruces, which is a shade tolerant tree species
- \triangleright Data inclusdes 249 stands, 1-4 measurement occasions with 5 years intervals
- \triangleright A total of 18056 height measurements, 3-49 trees per stand

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[Model development](#page-10-0) [Estimated model](#page-16-0)

Model for tree i in stand k at time t

Starting point is the Korf function

 $H = a \exp(-bD^{-c})$

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Model for tree i in stand k at time t

Starting point is the Korf function

$$
H = a \exp(-bD^{-c})
$$

I reparameterized D and linearized the model to get

$$
\ln(H_{kti}) = A_{kt} + B_{kt}x_{kti} + \epsilon_{kti}
$$
 (1)

The reparameterization of D_{kti} was

$$
x_{kti} = \frac{(D_{kti} + \lambda)^{-C} - (DGM + 10 + \lambda)^{-C}}{(30 + \lambda)^{-C} - (10 + \lambda)^{-C}},
$$

where $\lambda = 7$ cm and $C = 1.564$.

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[Model development](#page-8-0) [Estimated model](#page-16-0)

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Interpretations

A is the expected logarithmic height of thickest trees in the stand B is the difference in $ln(H)$ between trees of diameters 30 and 10 cm

Model development **Estimated model**

The variance function

The variance function Lused was

$$
var(\epsilon_{kti}) = \sigma^2 \big(\max(D_{kti}, 7.5)\big)^{-2\delta} \tag{2}
$$

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Model development **Estimated model**

Separate fits

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Model development **Estimated model**

Separate fits

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[Model development](#page-8-0) [Estimated model](#page-16-0)

Trend functions

A: Champman-Richards

$$
A_{kt} = p_{1a} + p_{2a} (1 - \exp(-p_{3a}DGM_{kt}))^{p_{4a}} + \alpha_k + \alpha_{kt}
$$
 (3)

B: linear

$$
B_{kt} = p_{1b} + p_{2b}DGM_{kt} + \beta_k + \beta_{kt}
$$

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[Model development](#page-8-0) [Estimated model](#page-16-0)

Complete model

I wrote the trend functions to model [1](#page-8-1) to obtain

$$
\begin{array}{rcl}\n\ln(H_{kti}) & = & p_{1a} + \alpha_k + \alpha_{kt} + p_{2a} z_{kt} \\
& & + (p_{1b} + \beta_k + \beta_{kt} + p_{2b} DGM_{kt}) x_{kti} + \epsilon_{kti}\n\end{array}
$$

where z_{kt} is the nonlinear part of trend function [3,](#page-14-0) which is treated as a transformation of DGM_{kt} :

$$
z_{kt} = \left(1 - \exp(-0.0651 D G M_{kt})\right)^{0.999}
$$

 α_k and β_k are correlated, normal, stand specific random parameters, α_{kt} and β_{kt} are correlated, normal, measurement occasion specific random parameters, and ϵ_{kti} are normal tree level errors with variance as given in [2.](#page-11-0)

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[Model development](#page-8-0) [Estimated model](#page-16-0)

Estimates

The parameter estimates and their standard errors were as follows

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Prediction of random effects

The sample tree heights of a new stand can be described by

$$
\mathbf{y} = \boldsymbol{\mu} + \mathbf{Z}\mathbf{b} + \boldsymbol{\epsilon} \,,
$$

where

y includes the observed sample tree heights,

 μ is the fixed part,

 $\mathbf{b} = (\begin{array}{cccc} \alpha_k & \beta_k & \alpha_{k1} & \beta_{k1} & \alpha_{k2} & \beta_{k2} & \dots \end{array})$ ' includes the random effects, Z is the corresponding design matrix, and

 ϵ includes the residuals.

Let us denote $var(b) = D$ and $var(\epsilon) = R$.

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[Linear predictor in this case](#page-17-0) [Example](#page-19-0) [Predicting DGM in the future](#page-21-0)

Utilizing the model

The variances and covariances between random effects and observed heights can be written as

$$
\left[\begin{array}{c} \mathbf{b} \\ \mathbf{y} \end{array}\right] \sim \left(\left[\begin{array}{c} \mathbf{0} \\ \mu \end{array}\right], \left[\begin{array}{cc} \mathbf{D} & \mathbf{DZ}' \\ \mathbf{ZD} & \mathbf{ZDZ}'+\mathbf{R} \end{array}\right]\right)
$$

The Empirical Best Linear Unbiased predictor of random effects is

$$
\widehat{\mathbf{b}} = \mathbf{DZ}'(\mathbf{Z}\mathbf{DZ}' + \mathbf{R})^{-1}(\mathbf{y} - \boldsymbol{\mu}).
$$

and the variance of prediction errors is

$$
var(\hat{\mathbf{b}} - \mathbf{b}) = \mathbf{D} - \mathbf{DZ}'(\mathbf{Z}\mathbf{DZ}' + \mathbf{R})^{-1}\mathbf{Z}\mathbf{D}
$$

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Example

Heights of one tree was measured 5 years ago and 2 trees at this year. The matrices and vectors are

$$
\mu = \left[\begin{array}{c} 2.59 \\ 2.11 \\ 2.99 \end{array}\right] \quad \mathbf{y} = \left[\begin{array}{c} 2.77 \\ 2.35 \\ 3.19 \end{array}\right]
$$

$$
\mathbf{Z} = \left[\begin{array}{rrrrrr} 1 & -0.36 & 1 & -0.36 & 0 & 0 \\ 1 & -1.22 & 0 & 0 & 1 & -1.22 \\ 1 & 0.058 & 0 & 0 & 1 & 0.058 \end{array} \right] \quad \mathbf{R} = \left[\begin{array}{rrrr} 0.008 & 0 & 0 \\ 0 & 0.016 & 0 \\ 0 & 0 & 0.004 \end{array} \right]
$$

$$
\mathbf{b} = \begin{bmatrix} \alpha_k \\ \beta_k \\ \alpha_{k1} \\ \beta_{k1} \\ \alpha_{k2} \\ \beta_{k2} \end{bmatrix} \quad \mathbf{D} = \begin{bmatrix} 0.0118 & 0.0028 & 0 & 0 & 0 & 0 \\ 0.0028 & 0.0092 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.0003 & 0.0004 & 0 & 0 \\ 0 & 0 & 0.0004 & 0.0005 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.0003 & 0.0004 \\ 0 & 0 & 0 & 0 & 0.0004 & 0.0005 \end{bmatrix}
$$

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Example

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Linear predictor in this case **Example** Predicting DGM in the future

Model for DGM

The model for DGM was

 $\ln(DGM_{kt}) = u + v \ln T_{kt} + u_k + e_{kt}$,

where $u = 0.33$, $v = 0.63$, $var(u_k) = 0.32^2$ and $var(e_{kt}) = 0.069^2$.

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Final remarks

 \triangleright The mixed modeling for longitudinal data was a good approach in this context. It makes it possible to flexibly move forward and backward in time, and to utilize mesurements from different points in time in prediction.

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- \triangleright The development of H-D curves was best modeled as a function of a variable describing the mean (or median) size of trees in the stand, instead of stand age. That could be a good approach also in other models.
- \triangleright R-sowtware has many good properties that make this kind of analysis easy in R: function 'unique', packages 'nlme' and 'lme', possibility to handle several datasets and models at same time.

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