Estimating forest attributes using observations of canopy height: a model-based approach

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Principle of Airborne laser scanning (ALS)

http://www.fgi.fi/osastot/projektisivut/kk_www_portaali/rswww/lasercase1.html

- \triangleright Scan half angle 0-10 degrees.
- \blacktriangleright Footprint diameter around 0.5 meters
- \blacktriangleright Pulse density about 0.5-5 pulses per m^2 .

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Data obtained by ALS

tietolähteenä. Metsätieteen aikakauskirja 4/2008.

Observations collected by laser scanner.

Kuva 1. Esimerkki koealan alueelle osuneista first pulse laserpisteistä muodostetusta korkeusiakaumasta.

From Suvento et al 2005. Kuxiokohtaisten puustotunnusten ennustaminen laserkeilauksella. Metsätieteen aikakauskirja 4/2005

Histogram of laser height observations from an example stand.

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Current approaches

In the area-based approach the forest area is divided into small grid cells, which are sampled for ground measurements. The approach is based on generalizing the estimated relationship between ground-measured and laser-scanned data from sampled cells to unsampled cells using the laser data.

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- \triangleright The area-based approach can be used with low-density laser data but ground-measured sample plots are always needed. It provides fairly accurate estimates of total volume, but predicting characteristics by tree species in a mixed stand is inaccurate.

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- In the individual tree detection approach, tree crowns are detected from the laser point cloud, and characteristics such as tree height and crown area are estimated for the detected trees. The total characteristics for a given area are estimated as aggregates of the detected trees.
- \triangleright The area-based approach can be used with low-density laser data but ground-measured sample plots are always needed. It provides fairly accurate estimates of total volume, but predicting characteristics by tree species in a mixed stand is inaccurate.
- \blacktriangleright The individual tree detection approach requires high-density laser data. However, only the largest trees can be detected, and trees forming dense groups are hard to separate. The species of recognized individual trees can be detected with sufficient accuracy when dealing with species that have different crown shapes.

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Forest inventory using laser scanning

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- \triangleright \triangleright \triangleright Several observations provide data of measured [can](#page-11-0)[opy](#page-13-0)h[ei](#page-12-0)[g](#page-13-0)[ht](#page-1-0)[s](#page-2-0)[.](#page-12-0)

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Canopy height (CH) vs tree height (TH)

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What kind of stand most likely produced the distribution of canopy heights we observed?

- \triangleright A single-species stand is characterized by distribution of tree heights and stand density.
- \triangleright The essential task is to state the distribution of canopy heights in terms of the distribution of tree heights and stand density.

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- \triangleright The essential task is to state the distribution of canopy heights in terms of the distribution of tree heights and stand density.

Then our question can be answered by fitting the recovered distribution to the observed data using Maximum Likelihood.

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General assumptions

- Forest stand A with area $|A|$ is a realization of a stochastic model defined by
	- ightharpoonup stand density λ (trees per m²),
	- \blacktriangleright the distribution of tree heights, and
	- \blacktriangleright the process that generates tree locations.

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- \triangleright Tree heights of the stand are i.i.d. realizations from a stand-specific height distribution $F(h|\xi)$, where ξ is a stand-specific parameter.

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- \triangleright Crown shape is a fixed, known function of tree height (e.g. ellipsoid).
- Random variable $Z(v)$ measures the vertical distance from ground level to the canopy surface, i.e., to the top of the canopy.

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A model for a single tree crown

- \blacktriangleright For a tree with height h, the cross-section at height $z \geq 0$ is the set $C_0(z, h)$ (gray).
	- \triangleright $C_0(z, h)$ is centered at the origin and
	- ► Points \overline{x} and $-x$ are included in it with equal probability (symmetry).

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 $C(z, h) = \bigcup_{z^* \geq z} C_0(z^*, h)$, so we forget C_0 and speak about \overline{C} from now on.

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- \triangleright $C(z, h)$ is empty when $z > h$, and area $|C(z, h)|$ decreases in z for fixed h.
- Denote a cross-section that is centered at u by $u + C(z, h)$.

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- \triangleright Denote a cross-section that is centered at u by $u + C(z, h)$.
- \blacktriangleright The asumption of symmetry guarantees that

 $P(u_2 \in u_1 + C(z, h)) \Leftrightarrow P(u_1 \in u_2 + C(z, h))$

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A model for a stand

Assume a stand with N trees at locations u_i , $i = 1, ..., N$ and random, i.i.d. heights H_i with distribution $F(h|\xi)$.

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A model for a stand

- Assume a stand with N trees at locations u_i , $i = 1, ..., N$ and random, i.i.d. heights H_i with distribution $F(h|\xi)$.
- **Consider canopy height** $Z(v)$ **at arbitrary location v.**

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- ► Now $Z(v) \ge z$ if for some i $v \in u_i + C(z, H_i)$.

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- Assume a stand with N trees at locations u_i , $i = 1, \ldots, N$ and random, i.i.d. heights H_i with distribution $F(h|\xi)$.
- Consider canopy height $Z(v)$ at arbitrary location v.
- Now $Z(v) > z$ if for some i $v \in u_i + C(z, H_i)$.
- \blacktriangleright In set theoretic language this means that $Z(v) \geq z \Leftrightarrow v \in \bigcup_{i=1}^N [u_i + C(z, H_i)].$

rom Matti Maltamo ym. 2008. Laserkeilaustulkinnan hyödyntäminen metsäsuunnittelui tietolähteens. Metsätieteen aikakauskirja 4/2006

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A model for a stand

 \blacktriangleright For the complement event, we get by De Morgans's law $Z(v) \leq z \Leftrightarrow v \in \bigcap_{i=1}^N [u_i + \overline{C}(z, H_i)]$

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- \triangleright Because of the symmetry of cross-sections and mutual independence of tree heights, we finally get

$$
P(Z(v) < z) = P[u_i \in v + \overline{C}(z, H_i), \text{ for all } i = 1, \ldots, N]
$$
\n
$$
= \prod_{i=1}^{N} P[u_i \in v + \overline{C}(z, H_i)],
$$

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A model for random tree locations

 \triangleright Assume that tree locations are generated by a spatial Poisson process with density λ . Then $N \sim Poisson(\lambda|A|)$ and locations u_i are uniformly distributed over A.

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	- \blacktriangleright Then we continue to condition on N but take the expectation over H_i , $i = 1, \ldots, N$.
	- Finally, the expectation over N yields the result.

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A model for random tree locations

$$
\begin{aligned}\n&\blacktriangleright \text{ We start with} \\
&\qquad E\left[E\left\{P\left(\bigcap_{i=1}^N[u_i\in v+\overline{C}(z,H_i)]\right)\bigm|N\right\}\right].\n\end{aligned}
$$

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- \triangleright We start with $E\left[E\left\{P\left(\bigcap_{i=1}^N[u_i \in v + \overline{C}(z, H_i)]\right) \middle| N\right\}\right].$
- In the innermost propability, each event has a conditional probability equal to the relative area $1 - |C(z, H_i)|/|A|$. By independence of events $E\left\{P\bigcap_{i=1}^N[u_i \in v + \overline{C}(z, H_i)]\middle| N\right\} = \left(1 - \frac{E(|C(z, H)|)}{|A|}\right)^N$

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- **► Finally,** $N \sim \text{Poisson}(\lambda |A|)$ **yields** $P(Z(v) < z) = \exp \{-\lambda E(|C(z, H)|)\}.$

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- **Finally, N** ∼ Poisson(λ |A|) yields $P(Z(v) < z) = \exp \{-\lambda E(|C(z, H)|)\}.$
- By continuity of $|C(z, h)|$ we have $P(Z(v) < z) = P(Z(v) \le z)$, when $z > 0$.

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- **Finally, N** ∼ Poisson(λ |A|) yields $P(Z(v) < z) = \exp \{-\lambda E(|C(z, H)|)\}.$
- By continuity of $|C(z, h)|$ we have $P(Z(v) < z) = P(Z(v) \le z)$, when $z > 0$.
- At $z = 0$ we have a point mass $P(Z(v) = 0) = \exp\{-\lambda E(|C(0, H)|)\}\,$, but naturally $P(Z(v) < 0) = 0$.

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- \triangleright We start with $E\left[E\left\{P\left(\bigcap_{i=1}^N[u_i \in v + \overline{C}(z, H_i)]\right) \middle| N\right\}\right].$
- \blacktriangleright In the innermost propability, each event has a conditional probability equal to the relative area $1 - |C(z, H_i)|/|A|$. By independence of events $E\left\{P\bigcap_{i=1}^N[u_i \in v + \overline{C}(z, H_i)]\middle| N\right\} = \left(1 - \frac{E(|C(z, H)|)}{|A|}\right)^N$
- **Finally, N** ∼ Poisson(λ |A|) yields $P(Z(v) < z) = \exp \{-\lambda E(|C(z, H)|)\}.$
- By continuity of $|C(z, h)|$ we have $P(Z(v) < z) = P(Z(v) \le z)$, when $z > 0$.
- At $z = 0$ we have a point mass $P(Z(v) = 0) = \exp\{-\lambda E(|C(0, H)|)\}\,$, but naturally $P(Z(v) < 0) = 0$.
- ► By homogeneity of the Poisson stand, $P(Z(v) \le z)$ applies to all locations $v \in A$.

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Distribution function and density

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- \triangleright The distribution function is the porosity of the model as a function of reference height z.

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 \blacktriangleright The parameters are estimated by using the method of maximum likelihood. The log likelihood under independnce of observations is

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\ell(\xi,\lambda)=\sum_{j=1}^M I(z_j>0)\log g(z_j|\xi,\lambda)+M_0\log G(0|\xi,\lambda)\,,
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where I is the indicator function and M_0 is the number of ground hits (for which $z_i = 0$).

Figure 1 The values of λ and ξ that maximize the log likelihood are the ML-estimates for stand density, and parameters of the height distribution. Asymptotic properties of ML-estimator can be used for to assess their accuracy and make inference.

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- \triangleright We assume independence of observations, which holds only for low spacing (no several observations per tree).
- \triangleright With dense spacing, estimates will still be asymptotically unbiased, but the standard errors will be downward biased. However, more efficient estimators maybe available that utilize the spatial autocorrelation of observations.

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Simulated data

 \triangleright We assumed that $H \sim$ Weibull(α, β).

 \triangleright Tree crowns were assumed ellipsoids with circular cross-section. Then $|C(z, h)| = \pi Y(z, h)^2$ and the squared crown radius is $Y(z, h)^2$ $Y(z, h)^2 =$
(0, \int \mathbf{I} 0, $0 \leq h < z$, $a(h)^2\left(1-\frac{\{z-b(h)\}^2}{\{b-b(h)\}^2}\right)$ $\frac{\{z-b(h)\}^2}{\{h-b(h)\}^2}\Big)\, , \quad z \leq h < b^{-1}(z),$ $a(h)^2$, $h \ge b^{-1}(z)$. where $a(h) = ph$ and $b(h) = qh$ with $p = 0.1$ and $q = 0.6$.

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Simulated data

It is clear that the point mass at $z = 0$ is $G(0 | \lambda, \xi) = \exp \{-\lambda \pi \int_0^\infty a(h)^2 f(h|\xi) dh\}.$

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- \triangleright We simulated with $\alpha \beta \lambda$ combinations 10-20-7, 10-20-4, 10-20-15, 5-10-7, and 20-25-7 (the unit for λ is trees per 100 m²).

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- \triangleright Each combination was simulated 500 times with 3 different densities: $M = 30$, $M = 100$ and $M = 400$ observations per 2000 m²

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- \triangleright Each combination was simulated 500 times with 3 different densities: $M = 30$, $M = 100$ and $M = 400$ observations per 2000 m²
- \triangleright The model was fitted using R-package function mle in package stats4.

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Example fits

One randomly selected fit for each of the five parameter combinations with the sample size of 100. The right panel shows the observations of canopy height (histogram) and the fitted density (solid line and diamond). The left panel shows the true tree heights (histogram) and the estimated distribution of the same plot. The numbers show the parameter estimates.

Estimating forest attributes using observations of canopy height: a model-b

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Simulation results

Bias of estimates of mean height (meters) and stand density (trees per ha) in different simulations. \overline{a}

 $M=$ number of observations, α and β Weibull parms, λ true number of stems. Sample plot area was $2000m^2$

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Bias, standard deviation and asymptotic s.e. of parameter estimates.

M=number of observations, α and β Weibull parms, λ true number of stems. Sample plot area was 2000m²

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Normal-Q-Q-plots of estimates

Normal Q-Q plots of estimates for the stand 10-20-7 with sample sizes of 30 (left) 100 (middle) and 400 (right).

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Lauri Mehtätalo¹ Estimating forest attributes using observations of canopy height: a model-b

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Tests with real data

- **Laser data 40 pulses/m² and aerial photographs from Tielaitos.**
- Ground data (20 plots of size $20*20m$). Species and dbh known for each tree.
- \triangleright Single tree from 18 plots were used for modeling crown shape (the models I showed earlier)
- \blacktriangleright Thinned "laser" data (0.25 pulsesper m²) of the rest two plots were used for method testing.

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Models for crown shape

Average crown shape for Spruce (solid) and Pine (dashed)

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Evaluation plots

Pure spruce stand $H = 17.77$ m $N=700$ stems/ha

Mixed spruce-pine stand $H_{\text{spruce}} = 9.87 \text{ m}$ $H_{pine} = 15.66$ m $N=1350$ stems/ha ρ =0.70 (70% were spruces)

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Plot 8 by assuming random locations

 \tilde{H} =15.12 m (true 17.77)

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Plot 8 by assuming square grid locations

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Plot 28 by assuming random locations

Discussion and conclusions

- \blacktriangleright First trials to derive stand characteristics by utilizing assumptions on crown shape, and a spatial model for the stand.
- \triangleright ML-estimation for the model seems to be quite stable and produces quite reliable estimates with simulated datasets
- \triangleright Comutationally intensive method as it needs nested application of numerical methods
- \triangleright Seems to be quite vulnerable to violation of asumptions on spatial pattern of tree locations
- \triangleright Could be a way to integrate the research on single tree crowns with the models of stand structure.
- \triangleright Could provide a theoretical basis for the so-callet area-based approach.

Publications

Mehtätalo, L. and Nyblom, J. Estimating forest parameters using observations of canopy height: a model-based approach. Forest Science 55(5): 411-422.

Mehtätalo, L. 2006. Eliminating the effect of overlapping crowns from aerial inventory estimates. Canadian Journal of Forest Research 36(7): 1649-1660. (Reprints available upon request)