Estimating forest attributes using observations of canopy height: a model-based approach

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September 29, 2009 Kvantitatiivisten menetelmien seminaari Joensuu, Finland Based on Mehtätalo, L. and Nyblom, J. 2009. Estimating forest attributes using observations of canopy height: a model-based approach. Forest Science 55(5): 411-422.

Outline of the presentation

Introduction

Forest inventory and laser scanning Our question

A model for canopy height

General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

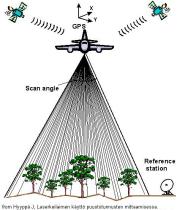
Evaluation and tests

Data		
Results		
Examples with	real	data

Discussion and conclusions

Forest inventory and laser scanning

Principle of Airborne laser scanning (ALS)

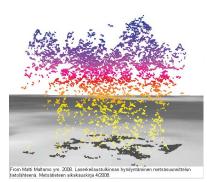


http://www.fgi.fi/osastot/projektisivut/kk_www_portaali/rswww/lasercase1.html

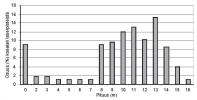
- Scan half angle 0-10 degrees.
- Footprint diameter around 0.5 meters
- Pulse density about 0.5-5 pulses ► per m².

Forest inventory and laser scanning Our question

Data obtained by ALS



Observations collected by laser scanner.



Kuva I. Esimerkki koealan alueelle osuneista first pulse laserpisteistä muodostetusta korkeusjakaumasta.

From Suvanto et al 2005. Kuviokohtaisten puustotumusten ennustaminen laserkeilauksella. Metsätieteen aikakauskirja 4/2005

Histogram of laser height observations from an example stand.

Forest inventory and laser scanning Our question

Current approaches

In the area-based approach the forest area is divided into small grid cells, which are sampled for ground measurements. The approach is based on generalizing the estimated relationship between ground-measured and laser-scanned data from sampled cells to unsampled cells using the laser data.

Forest inventory and laser scanning Our question

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- In the individual tree detection approach, tree crowns are detected from the laser point cloud, and characteristics such as tree height and crown area are estimated for the detected trees. The total characteristics for a given area are estimated as aggregates of the detected trees.

Forest inventory and laser scanning Our question

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- The area-based approach can be used with low-density laser data but ground-measured sample plots are always needed. It provides fairly accurate estimates of total volume, but predicting characteristics by tree species in a mixed stand is inaccurate.

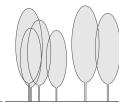
Forest inventory and laser scanning Our question

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- The area-based approach can be used with low-density laser data but ground-measured sample plots are always needed. It provides fairly accurate estimates of total volume, but predicting characteristics by tree species in a mixed stand is inaccurate.
- The individual tree detection approach requires high-density laser data. However, only the largest trees can be detected, and trees forming dense groups are hard to separate. The species of recognized individual trees can be detected with sufficient accuracy when dealing with species that have different crown shapes.

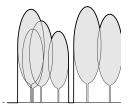
Forest inventory and laser scanning Our question

Forest inventory using laser scanning



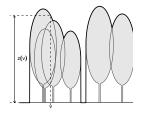
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Forest inventory and laser scanning Our question



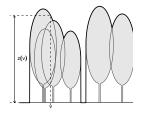
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- From above we can see only the surface of the forest stand (we regard it as solid).

Forest inventory and laser scanning Our question



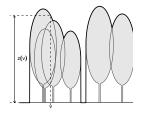
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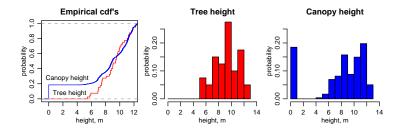
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- These observations are random because their location, tree heights, and tree locations may be random.
- Several observations provide data of measured canopy heights.

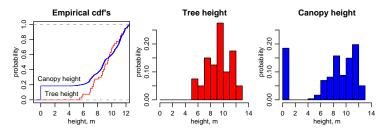
Forest inventory and laser scanning Our question

Canopy height (CH) vs tree height (TH)



Forest inventory and laser scanning Our question

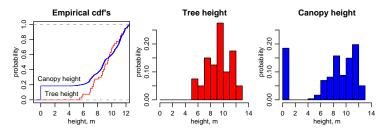
Canopy height (CH) vs tree height (TH)



What kind of stand most likely produced the distribution of canopy heights we observed?

Forest inventory and laser scanning Our question

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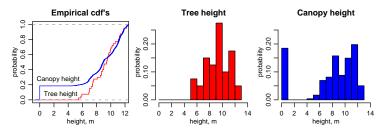


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 A single-species stand is characterized by distribution of tree heights and stand density.

Forest inventory and laser scanning Our question

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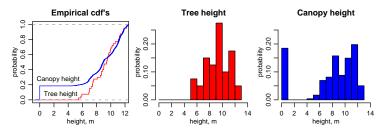


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- The essential task is to state the distribution of canopy heights in terms of the distribution of tree heights and stand density.

Forest inventory and laser scanning Our question

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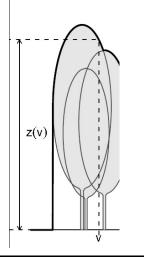
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- The essential task is to state the distribution of canopy heights in terms of the distribution of tree heights and stand density.

Then our question can be answered by fitting the recovered distribution to the observed data using Maximum Likelihood.

General assumptions

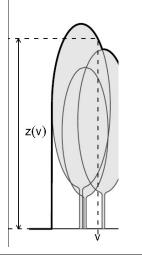
A model for single tree crown A model for a stand A model for random tree locations Estimation



- Forest stand A with area |A| is a realization of a stochastic model defined by
 - stand density λ (trees per m²),
 - the distribution of tree heights, and
 - the process that generates tree locations.

General assumptions

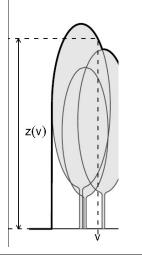
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General assumptions

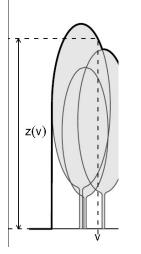
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- Tree heights of the stand are i.i.d. realizations from a stand-specific height distribution F(h|ξ), where ξ is a stand-specific parameter.

General assumptions

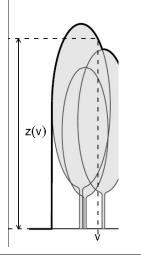
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- Crown shape is a fixed, known function of tree height (e.g. ellipsoid).

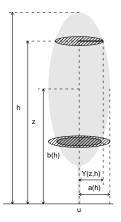
General assumptions

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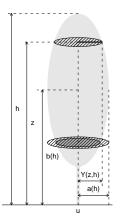
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- Crown shape is a fixed, known function of tree height (e.g. ellipsoid).
- Random variable Z(v) measures the vertical distance from ground level to the canopy surface, i.e., to the top of the canopy.

General assumptions **A model for single tree crown** A model for a stand A model for random tree locations Estimation



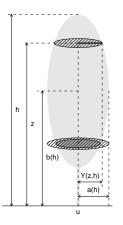
- For a tree with height *h*, the cross-section at height *z* ≥ 0 is the set C₀(*z*, *h*) (gray).
 - $C_0(z, h)$ is centered at the origin and
 - Points x and -x are included in it with equal probability (symmetry).

General assumptions **A model for single tree crown** A model for a stand A model for random tree locations Estimation



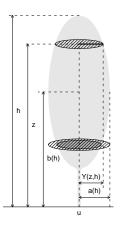
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- From above, we only can observe $C(z, h) = \bigcup_{z^* \ge z} C_0(z^*, h)$, so we forget C_0 and speak about C from now on.

General assumptions **A model for single tree crown** A model for a stand A model for random tree locations Estimation



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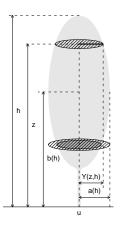
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- Denote a cross-section that is centered at u by u + C(z, h).

General assumptions **A model for single tree crown** A model for a stand A model for random tree locations Estimation

A model for a single tree crown



- For a tree with height h, the cross-section at height $z \ge 0$ is the set $C_0(z, h)$ (gray).
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- ► C(z, h) is empty when z > h, and area |C(z, h)| decreases in z for fixed h.
- Denote a cross-section that is centered at u by u + C(z, h).
- The asumption of symmetry guarantees that

 $P(u_2 \in u_1 + C(z,h)) \Leftrightarrow P(u_1 \in u_2 + C(z,h))$

General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

A model for a stand

Assume a stand with N trees at locations u_i , i = 1, ..., N and random, i.i.d. heights H_i with distribution $F(h|\xi)$.

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- Now $Z(v) \ge z$ if for some $i v \in u_i + C(z, H_i)$.

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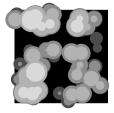
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- Consider canopy height Z(v) at arbitrary location v.
- Now $Z(v) \ge z$ if for some $i v \in u_i + C(z, H_i)$.
- ▶ In set theoretic language this means that $Z(v) \ge z \Leftrightarrow v \in \bigcup_{i=1}^{N} [u_i + C(z, H_i)].$



From Matti Maltamo ym. 2008. Laserkeilaustulkinnan hyddyntäminen metstasuurnittelun jetolähteenä. Metsätieteen aikakauskina 4/2008.





General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

A model for a stand

▶ For the complement event, we get by De Morgans's law $Z(v) \le z \Leftrightarrow v \in \bigcap_{i=1}^{N} [u_i + \overline{C}(z, H_i)]$

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- ▶ For the complement event, we get by De Morgans's law $Z(v) \le z \Leftrightarrow v \in \bigcap_{i=1}^{N} [u_i + \overline{C}(z, H_i)]$
- Because of the symmetry of cross-sections and mutual independence of tree heights, we finally get

$$P(Z(v) < z) = P[u_i \in v + \overline{C}(z, H_i), \text{ for all } i = 1, \dots, N]$$
$$= \prod_{i=1}^{N} P[u_i \in v + \overline{C}(z, H_i)],$$

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A model for random tree locations

Assume that tree locations are generated by a spatial Poisson process with density λ. Then N ~ Poisson(λ|A|) and locations u_i are uniformly distributed over A.

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General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

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 - Finally, the expectation over N yields the result.

General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

A model for random tree locations

• We start with
$$E\left[E\left\{P\left(\bigcap_{i=1}^{N}[u_i \in v + \overline{C}(z, H_i)]\right) \mid N\right\}\right].$$

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General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

- We start with $E\left[E\left\{P\left(\bigcap_{i=1}^{N}[u_i \in v + \overline{C}(z, H_i)]\right) \mid N\right\}\right].$
- ▶ In the innermost propability, each event has a conditional probability equal to the relative area $1 |C(z, H_i)|/|A|$. By independence of events $E \left\{ P \bigcap_{i=1}^{N} [u_i \in v + \overline{C}(z, H_i)] \middle| N \right\} = \left(1 \frac{E(|C(z, H|))}{|A|}\right)^N$

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$$E\left\{\left.P\bigcap_{i=1}^{N}\left[u_{i}\in v+\bar{C}(z,H_{i})\right]\right|N\right\}=\left(1-\frac{E\left(\left|C(z,H)\right|\right)}{\left|A\right|}\right)$$

Finally,
$$N \sim \text{Poisson}(\lambda|A|)$$
 yields
 $P(Z(v) < z) = \exp \{-\lambda E(|C(z, H)|)\}$

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- By continuity of |C(z, h)| we have $P(Z(v) < z) = P(Z(v) \le z)$, when z > 0.

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- By continuity of |C(z, h)| we have $P(Z(v) < z) = P(Z(v) \le z)$, when z > 0.
- At z = 0 we have a point mass P(Z(v) = 0) = exp {−λE(|C(0, H)|)}, but naturally P(Z(v) < 0) = 0.</p>
- By homogeneity of the Poisson stand, P(Z(v) ≤ z) applies to all locations v ∈ A.

General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

Distribution function and density

• The distribution function is $P(Z \le z) = G(z|\lambda, \xi) = \exp\left\{-\lambda \int_0^\infty |C(z, h)| f(h|\xi) dh\right\}$

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- ▶ If the area function |C(z, h)| is regular enough the density is $g(z|\lambda, \xi) = -\lambda G(z|\lambda, \xi) \frac{d}{dz} \int_0^\infty |C(z, h)| f(h|\xi) dh$

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General assumptions A model for single tree crown A model for a stand A model for random tree locations Estimation

Distribution function and density

- ► The distribution function is $P(Z \le z) = G(z|\lambda, \xi) = \exp \left\{-\lambda \int_0^\infty |C(z, h)| f(h|\xi) dh\right\}$
- ▶ If the area function |C(z, h)| is regular enough the density is $g(z|\lambda, \xi) = -\lambda G(z|\lambda, \xi) \frac{d}{dz} \int_0^\infty |C(z, h)| f(h|\xi) dh$
- The point mass at z = 0 is $G(0 \mid \lambda, \xi) = \exp \left\{-\lambda \int_0^\infty |C(0, h|f(h|\xi))dh\right\}$.

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- The distribution function is the porosity of the model as a function of reference height z.

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Estimation

The parameters are estimated by using the method of maximum likelihood. The log likelihood under independence of observations is

$$\ell(oldsymbol{\xi},\lambda) = \sum_{j=1}^M I(z_j>0) \log g(z_j|oldsymbol{\xi},\lambda) + M_0 \log G(0|oldsymbol{\xi},\lambda) \,,$$

where *I* is the indicator function and M_0 is the number of ground hits (for which $z_j = 0$).

The values of \u03c6 and \u03c6 that maximize the log likelihood are the ML-estimates for stand density, and parameters of the height distribution. Asymptotic properties of ML-estimator can be used for to assess their accuracy and make inference.

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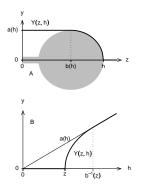
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- ► We assume independence of observations, which holds only for low spacing (no several observations per tree).
- With dense spacing, estimates will still be asymptotically unbiased, but the standard errors will be downward biased. However, more efficient estimators maybe available that utilize the spatial autocorrelation of observations.

Data Results Examples with real data

Simulated data



We assumed that H ~ Weibull(α, β).

► Tree crowns were assumed ellipsoids with circular cross-section. Then $\begin{aligned} |C(z,h)| &= \pi Y(z,h)^2 \text{ and the squared crown} \\ \text{radius is} \\ Y(z,h)^2 &= \\ \begin{cases} 0, & 0 \le h < z, \\ a(h)^2 \left(1 - \frac{\{z-b(h)\}^2}{\{h-b(h)\}^2}\right), & z \le h < b^{-1}(z), \\ a(h)^2, & h \ge b^{-1}(z). \\ \text{where } a(h) = ph \text{ and } b(h) = qh \text{ with } p = 0.1 \\ \text{and } q = 0.6. \end{aligned}$

Data Results Examples with real data

Simulated data

• It is clear that the point mass at z = 0 is $G(0 \mid \lambda, \xi) = \exp \left\{ -\lambda \pi \int_0^\infty a(h)^2 f(h|\xi) dh \right\}.$

3.1

Data Results Examples with real data

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4 E b

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- ▶ We simulated with $\alpha \beta \lambda$ combinations 10-20-7, 10-20-4, 10-20-15, 5-10-7, and 20-25-7 (the unit for λ is trees per 100 m²).

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- Each combination was simulated 500 times with 3 different densities: M = 30, M = 100 and M = 400 observations per 2000 m²

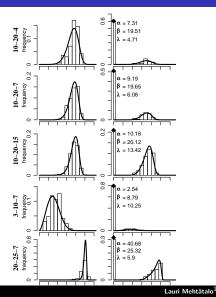
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- The model was fitted using R-package function mle in package stats4.

Data Results Examples with real data

Example fits



One randomly selected fit for each of the five parameter combinations with the sample size of 100. The right panel shows the observations of canopy height (histogram) and the fitted density (solid line and diamond). The left panel shows the true tree heights (histogram) and the estimated distribution of the same plot. The numbers show the parameter estimates.

Estimating forest attributes using observations of canopy height: a model-b

Data Results Examples with real data

Simulation results

Bias of estimates of mean height (meters) and stand density (trees per ha) in different simulations.

		M=30		M=100		M=400			
α - β - λ		Ē	N	Ē	N	Ē	N		
10-20-4	true mean	19.03	400	19.03	400	19.03	400		
	bias%	0.84	2.26	0.62	0.09	0.12	0.30		
	s.d.	1.21	148.53	0.67	78.16	0.36	53.56		
10-20-7	true mean	19.03	700	19.03	700	19.03	700		
	bias%	0.89	2.42	0.45	-1.66	0.07	0.43		
	s.d.	1.03	235.62	0.56	125.15	0.31	79.85		
10-20-15	true mean	19.03	1500	19.03	1500	19.03	1500		
	bias%	0.02	13.27	-0.05	2.76	-0.07	0.70		
	s.d.	1.08	2698.26	0.53	263.39	0.29	145.76		
3-10-7	true mean	8.93	700	8.93	700	8.93	700		
	bias%	6.65	1.76	1.45	3.20	0.65	-0.57		
	s.d.	2.27	480.08	1.24	238.60	0.66	122.87		
20-25-7	true mean	24.34	700	24.34	700	24.34	700		
	bias%	0.23	1.28	-0.08	2.12	0.02	0.40		
	s.d.	0.78	205.81	0.43	112.24	0.22	73.31		

M=number of observations, α and β Weibull parms, λ true number of stems. Sample plot area was 2000m²

Data Results Examples with real data

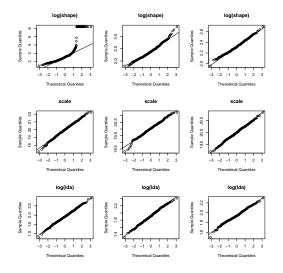
Bias, standard deviation and asymptotic s.e. of parameter estimates.

-			M=30		M=100		M=400			
		$\log(\widehat{\alpha})$	$\widehat{\beta}$	$\log(\widehat{\lambda})$	$\log(\widehat{\alpha})$	$\widehat{\beta}$	$\log(\widehat{\lambda})$	$\log(\widehat{\alpha})$	$\widehat{\beta}$	$\log(\widehat{\lambda})$
10-20-4	true mean	2.30	20	1.39	2.30	20	1.39	2.30	20	1.39
cc=0.37	bias	>0.967	-0.118	-0.046	>0.139	0.042	-0.019	0.034	-0.002	-0.006
	s.d.	1.580	0.988	0.379	0.422	0.545	0.200	0.136	0.310	0.134
	$\overline{\hat{\sigma}}$	1.179	0.824	0.348	0.296	0.514	0.187	0.126	0.263	0.093
10-20-7	true mean	2.30	20	1.95	2.30	20	1.95	2.30	20	1.95
cc=0.55	bias	>0.509	-0.011	-0.027	0.093	0.025	-0.033	0.018	0.002	-0.002
	sd	1.127	0.814	0.320	0.241	0.459	0.181	0.109	0.266	0.113
	$\overline{\hat{\sigma}}$	0.718	0.748	0.295	0.221	0.435	0.161	0.103	0.222	0.080
10-20-15	true mean	2.30	20	2.71	2.30	20	2.71	2.30	20	2.71
cc=0.82	bias	>0.162	-0.078	0.014	0.033	-0.031	0.013	0.005	-0.016	0.002
	sd	0.535	0.894	0.342	0.192	0.423	0.165	0.097	0.242	0.096
	$\overline{\hat{\sigma}}$	0.398	0.759	0.294	0.180	0.408	0.154	0.087	0.204	0.076
3-10-7	true mean	1.10	10	1.95	1.10	10	1.95	1.10	10	1.95
cc=0.18	bias	>1.221	0.226	-0.202	0.099	0.056	-0.024	0.033	0.038	-0.021
	sd	2.005	2.252	0.693	0.333	1.254	0.341	0.157	0.685	0.179
	$\overline{\hat{\sigma}}$	1.460	1.700	0.630	0.288	1.188	0.336	0.139	0.609	0.167
20-25-7	true mean	3.00	25	1.95	3.00	25	1.95	3.00	25	1.95
cc=0.73	bias	>0.640	-0.082	-0.027	0.054	-0.037	0.009	0.017	-0.001	-0.001
	sd	1.199	0.569	0.279	0.270	0.321	0.155	0.129	0.172	0.104
	ō	0.953	0.520	0.259	0.266	0.313	0.141	0.124	0.156	0.070

M=number of observations, α and β Weibull parms, λ true number of stems. Sample plot area was 2000m²

Data Results Examples with real data

Normal-Q-Q-plots of estimates



Normal Q-Q plots of estimates for the stand 10-20-7 with sample sizes of 30 (left) 100 (middle) and 400 (right).

-

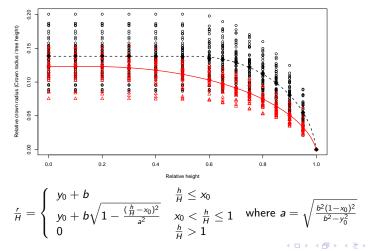
Data Results Examples with real data

Tests with real data

- ► Laser data 40 pulses/m² and aerial photographs from Tielaitos.
- Ground data (20 plots of size 20*20m). Species and dbh known for each tree.
- Single tree from 18 plots were used for modeling crown shape (the models I showed earlier)
- Thinned "laser" data (0.25 pulsesper m²) of the rest two plots were used for method testing.

Data Results Examples with real data

Models for crown shape



Average crown shape for Spruce (solid) and Pine (dashed)

Lauri Mehtätalo¹ Estimating forest attributes using observations of canopy height: a model-b

Data Results Examples with real data

Evaluation plots



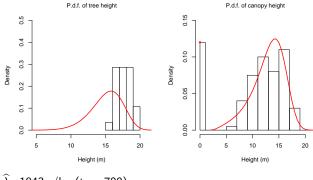
Pure spruce stand \bar{H} =17.77 m N=700 stems/ha



Mixed spruce-pine stand $H_{spruce}^{-}=9.87 \text{ m}$ $H_{pine}^{-}=15.66 \text{ m}$ N=1350 stems/ha $\rho=0.70 (70\% \text{ were spruces})$

Data Results Examples with real data

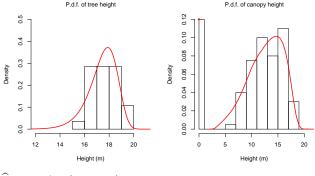
Plot 8 by assuming random locations



 $\widehat{\lambda}$ =1943 r/ha (true 700) \widehat{H} =15.12 m (true 17.77)

Data Results Examples with real data

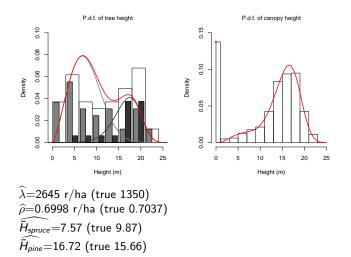
Plot 8 by assuming square grid locations



 $\widehat{\lambda}$ =642 r/ha (true 700) \widehat{H} =17.52 m (true 17.77)

Data Results Examples with real data

Plot 28 by assuming random locations



Discussion and conclusions

- First trials to derive stand characteristics by utilizing assumptions on crown shape, and a spatial model for the stand.
- ML-estimation for the model seems to be quite stable and produces quite reliable estimates with simulated datasets
- Comutationally intensive method as it needs nested application of numerical methods
- Seems to be quite vulnerable to violation of asumptions on spatial pattern of tree locations
- Could be a way to integrate the research on single tree crowns with the models of stand structure.
- Could provide a theoretical basis for the so-callet area-based approach.

Publications

Mehtätalo, L. and Nyblom, J. Estimating forest parameters using observations of canopy height: a model-based approach. Forest Science 55(5): 411-422.

Mehtätalo, L. 2006. Eliminating the effect of overlapping crowns from aerial inventory estimates. Canadian Journal of Forest Research 36(7): 1649-1660. (Reprints available upon request)